

UM12

Ultrasonic sensor

SICK
Sensor Intelligence.



Described product

UM12

Manufacturer

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Original document

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1 About this document

1.1 Information on the operating instructions

These operating instructions provide important information on how to use devices from SICK AG.

Prerequisites for safe work are:

- Compliance with all safety notes and handling instructions supplied.
- Compliance with local work safety regulations and general safety regulations for device applications

The operating instructions are intended to be used by qualified personnel and electrical specialists.



NOTE

Read these operating instructions carefully to familiarize yourself with the device and its functions before commencing any work.

The operating instructions are an integral part of the product. Store the instructions in the immediate vicinity of the device so they remain accessible to staff at all times. Should the device be passed on to a third party, these operating instructions should be handed over with it.

These operating instructions do not provide information on operating the machine or system in which the device is integrated. Information on this can be found in the operating instructions for the machine or system.

1.2 Explanation of symbols

Warnings and important information in this document are labeled with symbols. Signal words introduce the instructions and indicate the extent of the hazard. To avoid accidents, damage, and personal injury, always comply with the instructions and act carefully.



DANGER

... indicates a situation of imminent danger, which will lead to a fatality or serious injuries if not prevented.



WARNING

... indicates a potentially dangerous situation, which may lead to a fatality or serious injuries if not prevented.



CAUTION

... indicates a potentially dangerous situation, which may lead to minor/slight injuries if not prevented.



NOTICE

... indicates a potentially harmful situation, which may lead to material damage if not prevented.



NOTE

... highlights useful tips and recommendations as well as information for efficient and trouble-free operation.

1.3 Further information



NOTE

Further documentation for the device can be found on the online product page at:

- www.sick.com/UM12

Additional information is available there, depending on the product, e.g.:

- Model-specific online data sheets for device types, containing technical data, dimensional drawing, and specification diagrams
 - EU declaration of conformity and certificates of the product family
 - Dimensional drawings and 3D CAD dimension models of the device types in various electronic formats
 - Other publications related to the devices described here
 - Publications dealing with accessories
-

2 Safety information

2.1 Intended use

The UM12 ultrasonic sensor is used for non-contact detection and distance measurement. Distance measurement is not possible below the operating range of the device.

SICK AG assumes no liability for losses or damage arising from the use of the product, either directly or indirectly. This applies in particular to use of the product that does not conform to its intended purpose and is not described in this documentation.

2.2 Improper use

Any use outside of the stated areas, in particular use outside of the technical specifications and the requirements for intended use, will be deemed to be incorrect use.

- The device does not constitute a safety component in accordance with the respective applicable safety standards for machines.
- The device must not be used in explosion-hazardous areas, in corrosive environments or under extreme environmental conditions.
- Any use of accessories not specifically approved by SICK AG is at your own risk.



WARNING

Danger due to improper use!

Any improper use can result in dangerous situations.

Therefore, observe the following information:

- Product should be used only in accordance with its intended use.
- All information in these operating instructions must be strictly observed.
- Shut down the product immediately in case of damage.

2.3 Cybersecurity

To protect against cybersecurity threats, it is necessary to continuously monitor and maintain a comprehensive and holistic cybersecurity concept. A suitable concept comprises organizational, technical, procedural, electronic, and physical levels of defense and provides suitable measures for different types of risks. SICK's products and solutions must be viewed as a component of this concept.

Information on Cybersecurity can be found at: www.sick.com/psirt.

2.4 Limitation of liability

Relevant standards and regulations, the latest technological developments, and our many years of knowledge and experience have all been taken into account when compiling the data and information contained in these operating instructions. The manufacturer accepts no liability for damage caused by:

- Non-adherence to the product documentation (e.g., operating instructions)
- Incorrect use
- Use of untrained staff
- Unauthorized conversions or repair
- Technical modifications
- Use of unauthorized spare parts, consumables, and accessories

2.5 Modifications and conversions



NOTICE

Modifications and conversions to the device may result in unforeseeable dangers.

Interrupting or modifying the device or SICK software will invalidate any warranty claims against SICK AG. This applies in particular to opening the housing, even as part of mounting and electrical installation.

2.6 Requirements for skilled persons and operating personnel



WARNING

Risk of injury due to insufficient training.

Improper handling of the device may result in considerable personal injury and material damage.

- All work must only ever be carried out by the stipulated persons.

The following qualifications are required for various activities:

Table 1: Activities and technical requirements

Activities	Qualification
Mounting, maintenance	<ul style="list-style-type: none"> ■ Basic practical technical training ■ Knowledge of the current safety regulations in the workplace
Electrical installation, device replacement	<ul style="list-style-type: none"> ■ Practical electrical training ■ Knowledge of current electrical safety regulations ■ Knowledge of the operation and control of the devices in their particular application
Commissioning, configuration	<ul style="list-style-type: none"> ■ Basic knowledge of the computer operating system used ■ Basic knowledge of the design and setup of the described connections and interfaces ■ Basic knowledge of data transmission
Operation of the device for the particular application	<ul style="list-style-type: none"> ■ Knowledge of the operation and control of the devices in their particular application ■ Knowledge of the software and hardware environment for the particular application

2.7 Operational safety and particular hazards

Please observe the safety notes and the warnings listed here and in other sections of this production documentation to reduce the possibility of risks to health and avoid dangerous situations.



WARNING

Electrical voltage!

Electrical voltage can cause severe injury or death.

- Work on electrical systems must only be performed by qualified electricians.
- The power supply must be disconnected when attaching and detaching electrical connections.
- The product must only be connected to a voltage supply as set out in the requirements in the operating instructions.
- National and regional regulations must be complied with.
- Safety requirements relating to work on electrical systems must be complied with.

**WARNING****Risk of injury and damage caused by potential equalization currents!**

Improper grounding can lead to dangerous equipotential bonding currents, which may in turn lead to dangerous voltages on metallic surfaces, such as the housing. Electrical voltage can cause severe injury or death.

- Work on electrical systems must only be performed by qualified electricians.
- Follow the notes in the operating instructions.
- Install the grounding for the product and the system in accordance with national and regional regulations.

2.8 UL conformity

The UL certification is dependent on the type. Any existing UL certification can be found on the type label.



NFPA79 applications only. Adapters including field wiring cables are available.

For more information visit:

- www.sick.com/UM12

3 Product description

3.1 Scope of delivery

The delivery of the device includes the following components:

No. of units	Component	Remarks
1	Device in the version ordered	Device versions <ul style="list-style-type: none"> Digital output without IO-Link Digital output with IO-Link Analog output
1	Printed safety notes, multilingual	Brief information and general safety notes

Accessories are only supplied if you order them separately, see "Accessories", page 31.

With special variants, where optional extras have been ordered, or owing to the latest technical changes, the actual scope of delivery may vary from the features and illustrations shown here.

3.2 Product ID

Packaging

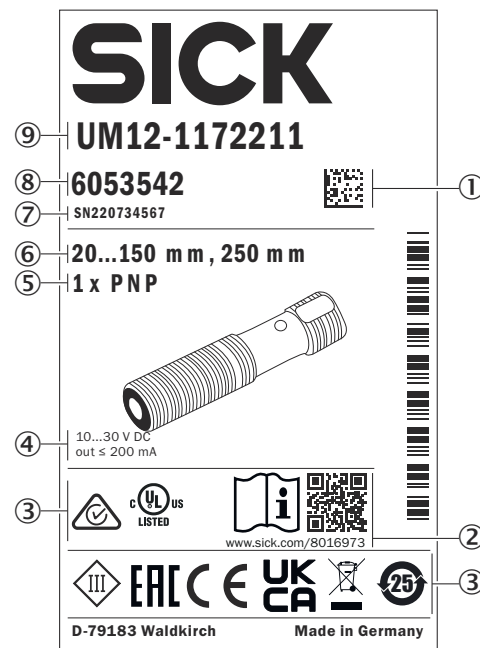


Figure 1: Packaging (example)

- ① Data Matrix code with product data
- ② Link to the operating instructions
- ③ Approval marks and test symbols
- ④ Supply voltage and output current
- ⑤ Interface
- ⑥ Operating range and limiting range
- ⑦ Serial number
- ⑧ Part number
- ⑨ Type code

Type label

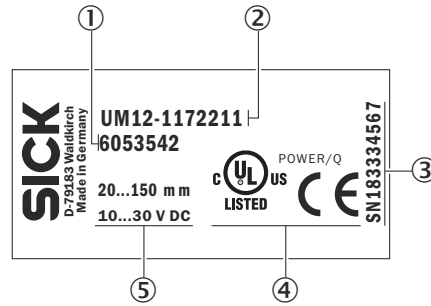


Figure 2: Type label (example)

- ① Part number
- ② Type code
- ③ Serial number
- ④ Approval marks and test symbols
- ⑤ Operating range and supply voltage

3.3 Type code

The devices of the UM12 product family are arranged according to the following type code:

UM12	-	1	1	x	2	2	x	1
1	-	2	3	4	5	6		

Table 2: Type code

Position	Description	Characteristic
1	Device name type	UM12: Ultrasonic, metric thread, 12 mm diameter
-		
2	Generation	1: 1. generation
3	Principle of operation	1: Button operation
4	Detection range, mounting distance (UD)	7: 20 mm ... 150 mm 9: 40 mm ... 240 mm
5	Connectivity	2: Male connector M12, 4-pin
6	Housing version	2: Nickel-plated brass
7	Output function	1: 1 x PNP 5: 1 x NPN 6: Analog, current interface 7: Analog, voltage interface B: 1 x push-pull: PNP/NPN with IO-Link 1.1
8	Alignment	1: Straight



NOTE

Not all combinations based on type code are possible. The available device types can be found online at www.sick.com/UM12.

3.4 Setup and dimensions

UM12-xxxxx1x, UM12-xxxxx5x, UM12-xxxxxBx

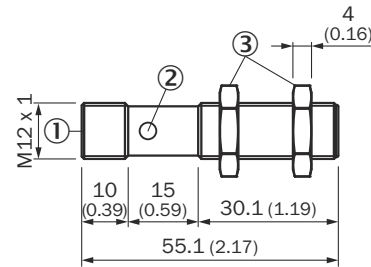


Figure 3: structure and device dimensions, unit: mm (inch), decimal separator: period

- ① Connection
- ② Display (2 status LEDs)
- ③ Fixing nuts, width 17 mm

UM12-xxxxx6x, UM12-xxxxx7x

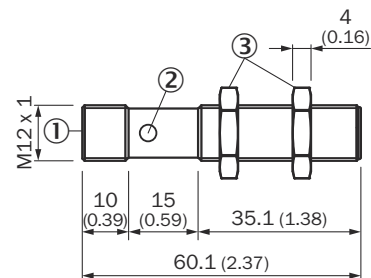
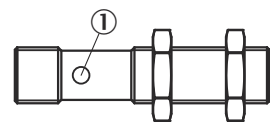


Figure 4: structure and device dimensions, unit: mm (inch), decimal separator: period

- ① Connection
- ② Display (2 status LEDs)
- ③ Fixing nuts, width 17 mm

3.5 Status indicators



- ① Display (2 status LEDs)

The display consists of two status LEDs behind an opening in the housing.

LED	Status (color)	Status
Status LED: Supply voltage active	● (Green)	Device ready
	IO-Link operation: ● (green)	

LED	Status (color)	Status
Status LED: digital output or analog output	● (Orange)	Digital output: digital output active Analog output: object in scaling range
	☀ (Orange) Flashes quickly for 3 seconds.	Teach-in: <ul style="list-style-type: none"> • No object detected • Object outside the detection range • First switching point within and second switching point outside the detection range ¹⁾ • Scaling < 1 mm taught-in ²⁾ The existing switching points are retained.

● = Lights up; ☀ = Flashes; ○ = Does not light up.

1) Applies to the switching window and ObSB switching modes.

2) Applies when teaching in the analog output.

3.6 Temperature compensation

The internal temperature compensation reaches the optimal operating point after an uptime of 1 minute. The temperature compensation is factory calibrated for the standard mounting conditions using an aluminum mounting bracket and mounting screws. The temperature compensation is automatically calibrated for the specific installation situation under the conditions specified below.

Conditions for automatic calibration

- The device is in a cold state.
- Digital output: The digital output is deactivated for approx. 30 minutes.
- Analog output: The analog output delivers a constant value of 11 mA ... 13 mA or 4.4 V ... 5.6 V for approx. 30 minutes.

If the measured value changes during the 30 minutes, the calibration is aborted. The standard parameters or the parameters last calibrated are retained. The automatic calibration is suitable for installation situations that differ greatly from the standard mounting conditions or where a high measurement accuracy is required. One example is thermally insulated mounting.

4 Transport and storage

4.1 Transport

For your own safety, please read and observe the following notes:



NOTICE

Damage to the product due to improper transport.

- The device must be packaged for transport with protection against shock and damp.
- Recommendation: Use the original packaging as it provides the best protection.
- Transport should be performed by trained specialist staff only.
- The utmost care and attention is required at all times during unloading and transportation on company premises.
- Note the symbols on the packaging.
- Do not remove packaging until immediately before you start mounting.

4.2 Unpacking

- To protect the device against condensation, allow it to equilibrate with the ambient temperature before unpacking if necessary.
- Handle the device with care and protect it from mechanical damage.

4.3 Transport inspection

Immediately upon receipt in Goods-in, check the delivery for completeness and for any damage that may have occurred in transit. In the case of transit damage that is visible externally, proceed as follows:

- Do not accept the delivery or only do so conditionally.
- Note the scope of damage on the transport documents or on the transport company's delivery note.
- File a complaint.



NOTE

Complaints regarding defects should be filed as soon as these are detected. Damage claims are only valid before the applicable complaint deadlines.

4.4 Storage

Store the device under the following conditions:

- Recommendation: Use the original packaging.
- Do not store outdoors.
- Store in a dry area that is protected from dust.
- Do not expose to any aggressive substances.
- Protect from sunlight.
- Avoid mechanical shocks.
- Storage temperature: [see "Technical data", page 27](#).
- For storage periods of longer than 3 months, check the general condition of all components and packaging on a regular basis.

5 Mounting

5.1 Mounting instructions

- Observe the technical data.
- To prevent condensation, avoid exposing the device to rapid changes in temperature.
- The mounting site has to be designed for the weight of the device.
- When using multiple devices, observe the mounting distance, see "Mounting distances", page 15.

5.2 Mounting distances

Table 3: Mounting distances

Device type	Parallel	Opposite
UM12-117x	> 250 mm	> 1300 mm
UM12-119x	> 250 mm	> 1400 mm

5.3 Aligning the device

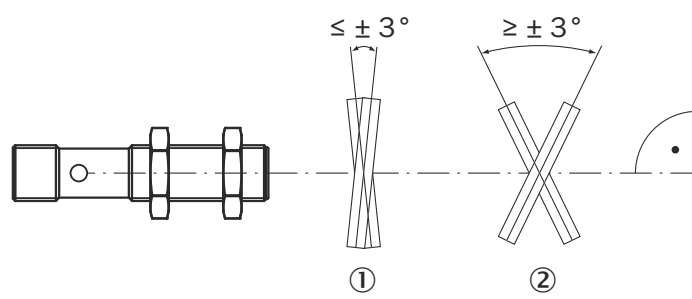


Figure 5: Aligning the device for smooth and rough surfaces

- ① Smooth surface: Angle $\leq 90^\circ \pm 3^\circ$ between the sensor axis and object surface
- ② Rough surface: Angle $\geq 90^\circ \pm 3^\circ$ between the sensor axis and object surface

6 Electrical installation

6.1 Wiring instructions



NOTE

Pre-assembled cables can be found online at:

- www.sick.com/UM12



NOTICE

Faults during operation and device or system defects!

Incorrect wiring may result in operational faults and defects.

- Follow the wiring notes precisely.

The enclosure rating stated in the technical data is achieved only with a screwed plug connector or protective cap.

Connect the connecting cables in a de-energized state. Do not switch on the supply voltage until installation is complete and all connecting cables are connected to the device and control.

The supply voltage must be as specified in the technical data, see "Technical data", page 27.

When commissioning, protect the device from moisture and contamination.

6.2 Prerequisites for safe operation of the device



WARNING

Risk of injury and damage caused by electrical current!

As a result of equipotential bonding currents between the device and other grounded devices in the system, faulty grounding of the device can give rise to the following dangers and faults:

- Dangerous voltages are applied to the metal housings.
- Devices will behave incorrectly or be destroyed.
- Cable shielding will be damaged by overheating and cause cable fires.

Remedial measures

- Only skilled electricians should be permitted to carry out work on the electrical system.
- If the cable insulation is damaged, disconnect the voltage supply immediately and have the damage repaired.
- Ensure that the ground potential is the same at all grounding points.
- Where local conditions do not meet the requirements for a safe earthing method, take appropriate measures. For example, ensure low-impedance and current-carrying equipotential bonding.

The device is connected to the peripheral devices (any local trigger sensor(s), system controller) via shielded cables. The cable shield – for the data cable, for example – rests against the metal housing of the device.

The device can be grounded through the cable shield or through a blind tapped hole in the housing, for example.

If the peripheral devices have metal housings and the cable shields are also in contact with their housings, it is assumed that all devices involved in the installation have the **same ground potential**.

This is achieved by complying with the following conditions:

- Mounting the devices on conductive metal surfaces
- Correctly grounding the devices and metal surfaces in the system
- If necessary: low-impedance and current-carrying equipotential bonding between areas with different ground potentials

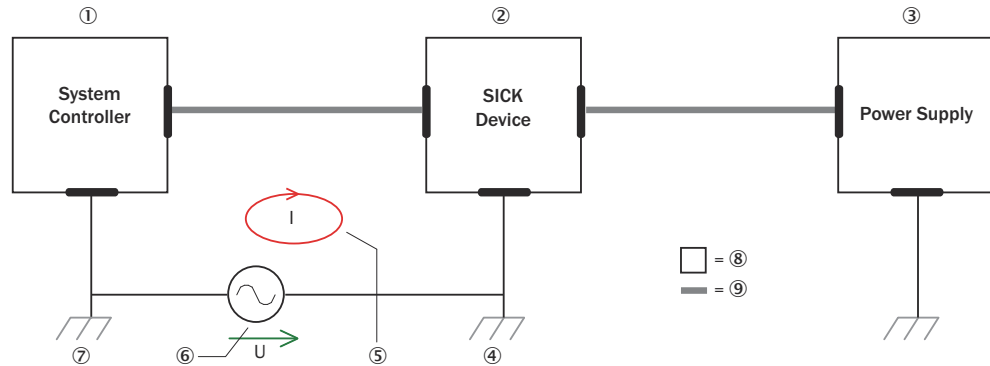


Figure 6: Example: Occurrence of equipotential bonding currents in the system configuration

- ① System controller
- ② Device
- ③ Voltage supply
- ④ Grounding point 2
- ⑤ Closed current loop with equalizing currents via cable shield
- ⑥ Ground potential difference
- ⑦ Grounding point 1
- ⑧ Metal housing
- ⑨ Shielded electrical cable

If these conditions are not fulfilled, equipotential bonding currents can flow along the cable shielding between the devices due to differing ground potentials and cause the hazards specified. This is, for example, possible in cases where there are devices within a widely distributed system covering several buildings.

Remedial measures

The most common solution to prevent equipotential bonding currents on cable shields is to ensure low-impedance and current-carrying equipotential bonding. If this equipotential bonding is not possible, the following solution approaches serve as a suggestion.



NOTICE

We expressly advise against opening up the cable shields. This would mean that the EMC limit values can no longer be complied with and that the safe operation of the device data interfaces can no longer be guaranteed.

Measures for widely distributed system installations

On widely distributed system installations with correspondingly large potential differences, the setting up of local islands and connecting them using commercially available **electro-optical signal isolators** is recommended. This measure achieves a high degree of resistance to electromagnetic interference.

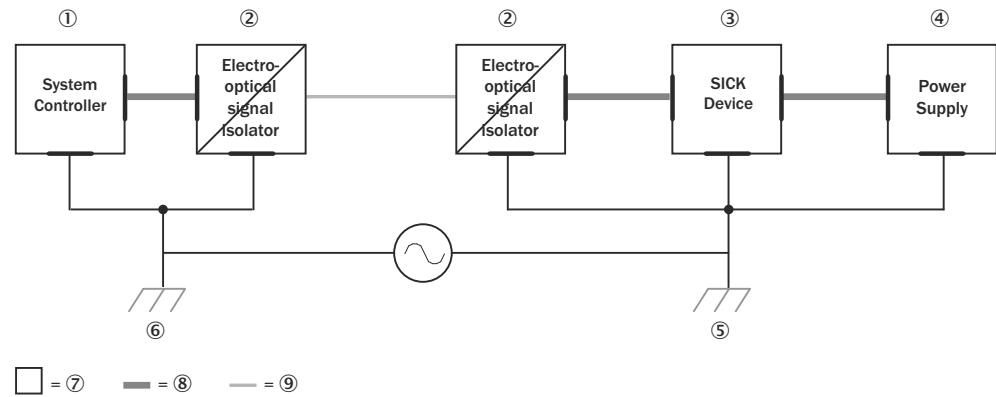


Figure 7: Example: Prevention of equipotential bonding currents in the system configuration by the use of electro-optical signal isolators

- ① System controller
- ② Electro-optical signal isolator
- ③ Device
- ④ Voltage supply
- ⑤ Grounding point 2
- ⑥ Grounding point 1
- ⑦ Metal housing
- ⑧ Shielded electrical cable
- ⑨ Optical fiber

The use of electro-optical signal isolators between the islands isolates the ground loop. Within the islands, a stable equipotential bonding prevents equalizing currents on the cable shields.

Measures for small system installations

For smaller installations with only slight potential differences, insulated mounting of the device and peripheral devices may be an adequate solution.

Even in the event of large differences in the ground potential, ground loops are effectively prevented. As a result, equalizing currents can no longer flow via the cable shields and metal housing.



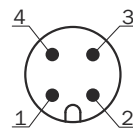
NOTICE

The voltage supply for the device and the connected peripheral devices must also guarantee the required level of insulation.

Under certain circumstances, a tangible potential can develop between the insulated metal housings and the local ground potential.

6.3 Pin assignment

UM12-xxxxx1x, UM12-xxxxx5x



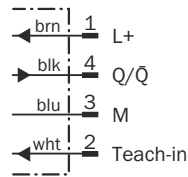


Figure 8: Male connector, M12, 4-pin

Table 4: Pin assignment for UM12-xxxxx1x, UM12-xxxxx5x

Contact	Signs	Wire color	Description
1	L+	Brown	Supply voltage, see "Mechanics/Electronics", page 27
2	Teach-in	White	Device teach-in
3	M	Blue	Supply voltage: 0 V
4	Q/Q̄	Black	Digital output / inverted digital output

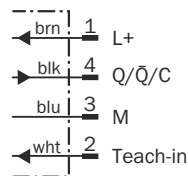
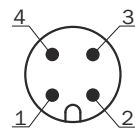
UM12-xxxxxBx

Figure 9: Male connector, M12, 4-pin

Table 5: Pin assignment for UM12-xxxxxBx

Contact	Signs	Wire color	Description
1	L+	Brown	Supply voltage, see "Mechanics/Electronics", page 27
2	Teach-in	White	Device teach-in
3	M	Blue	Supply voltage: 0 V
4	Q/Q̄/C	Black	Digital input / inverted digital output / IO-Link

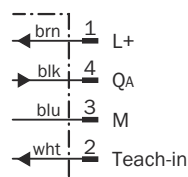
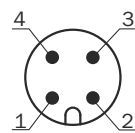
UM12-xxxxx6x, UM12-xxxxx7x

Figure 10: Male connector, M12, 4-pin

Table 6: Pin assignment for UM12-xxxxx6x, UM12-xxxxx7x

Contact	Signs	Wire color	Description
1	L+	Brown	Supply voltage, see "Mechanics/Electronics", page 27
2	Teach-in	White	Device teach-in
3	M	Blue	Supply voltage: 0 V
4	Q _A	Black	Analog output

7 Operation

7.1 LED behavior during teach-in

The status LED supports the teach-in process, see "Status indicators", page 12.

7.2 Teaching in the digital output

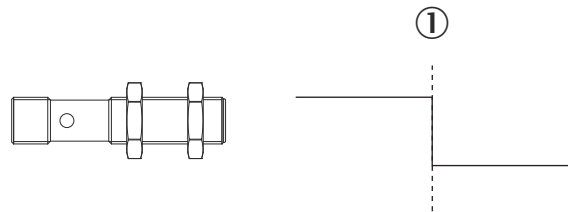
7.2.1 Factory settings of the digital output

- N/O contact
- Switching point (DtO) at maximum operating range

7.2.2 Teaching in the switching point, IO-Link: Single point (DtO) or single point + 8% (DtO + 8%)

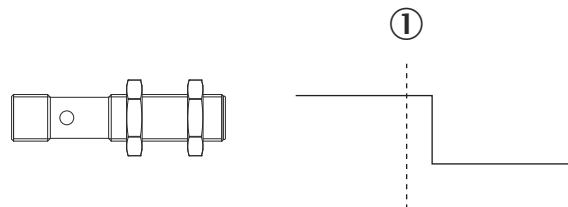
When the object is located below the taught-in switching point, the digital output is active.

Teaching in the switching point (distance to object as switching point)



1. Position the object at ①.
2. Apply L+ at Teach-in for 3 seconds until both LEDs are flashing simultaneously.
✓ Both LEDs flash alternately.
3. Apply L+ at Teach-in for 1 second.
✓ The switching point is taught in. The device automatically switches to normal operation mode.

Teaching in the switching point + 8% (distance + 8% as switching point)

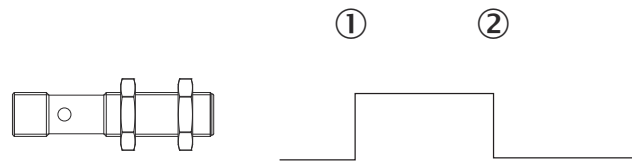


1. Position the object at ①.
2. Apply L+ at Teach-in for 3 seconds until both LEDs are flashing simultaneously.
✓ Both LEDs flash alternately.
3. Apply L+ at Teach-in for 3 seconds until both LEDs are again flashing alternately.
✓ The switching point is taught in. The device automatically switches to normal operation mode.

7.2.3 Teaching in the switching window, IO-Link: Window (window mode)

When the object is located within the taught-in switching window, the digital output is active.

Teach in the switching window



1. Position the object at ①.
2. Apply L+ at Teach-in for 3 seconds until both LEDs are flashing simultaneously.
 - ✓ Both LEDs flash alternately.
3. Position the object at ②.
- ✓ Both LEDs flash alternately.
4. Apply L+ at Teach-in for 1 second.
- ✓ The switching points are taught-in. The device automatically switches to normal operation mode.

7.2.4 Teaching in the background, IO-Link: Window $\pm 8\%$ (ObSB)

When the object is located either below the taught-in reflector distance - 8% or above the taught-in reflector distance + 8%, the digital output is active.

Teach in the background

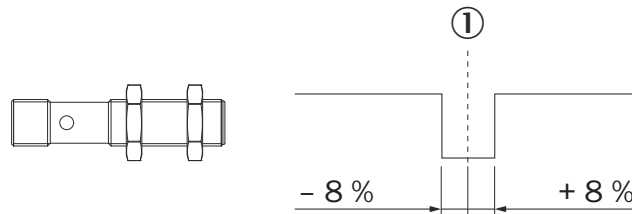


Figure 11: UM12-xxxxBx

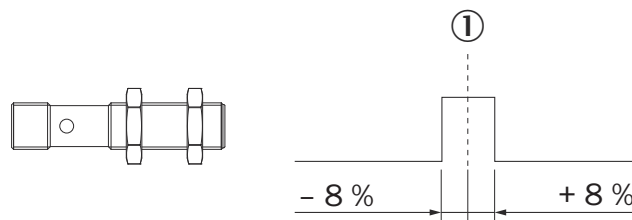


Figure 12: UM12-xxxx1x, UM12-xxxx5x

1. Position the background at ①.
2. Apply L+ at Teach-in for 3 seconds until both LEDs are flashing simultaneously.
 - ✓ Both LEDs flash alternately.
3. Apply L+ at Teach-in for 10 seconds until both LEDs stop flashing.
- ✓ The background is taught-in. The device automatically switches to normal operation mode.

7.2.5 Adjusting the N/C contact and N/O contact

1. Apply L+ at Teach-in for 13 seconds until both LEDs flash alternately.
 - ✓ Green LED flashes.
 - ✓ N/O: Orange LED lights up.
 - ✓ N/C: Orange LED does not light up.
2. To change the setting, apply L+ at Teach-in for 1 second.
 - ✓ Orange LED changes its status.
3. Wait 10 seconds.
 - ✓ Green LED no longer flashes.
 - ✓ N/C and N/O are adjusted. The device automatically switches to normal operation mode.

7.3 Teaching in the analog output

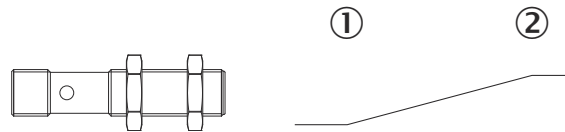
7.3.1 Factory settings of the analog output

- Rising output characteristic from minimum to maximum operating range

7.3.2 Scaling the analog output

To scale the analog output, teach-in a close sensor and distant sensor scaling limit. If the distant sensor scaling limit is taught-in first and then the close sensor scaling limit, the limits are reversed internally.

Teaching in the scaling limits



1. Position the object at ①.
2. Apply L+ at MF for 3 seconds until both LEDs are flashing simultaneously.
✓ Both LEDs flash alternately.
3. Position the object at ②.
4. Apply L+ at MF for 1 second.
✓ The scaling is taught-in. The device automatically switches to normal operation mode.

7.3.3 Adjusting the rising or falling output characteristic

1. Apply L+ at MF for 13 seconds until both LEDs flash alternately.
✓ Green LED flashes.
✓ Rising: Orange LED lights up.
✓ Falling: Orange LED does not light up.
2. To change the setting, apply L+ at MF for 1 second.
✓ Orange LED changes its status.
3. Wait 10 seconds.
✓ Green LED no longer flashes.
✓ The rising and falling output characteristic are adjusted. The device automatically switches to normal operation mode.

7.4 Resetting the device to factory settings

1. Switch off the supply voltage.
2. Apply L+ at Teach-in.
3. Switch on the supply voltage.
4. Wait 13 seconds until both LEDs are flashing simultaneously.
5. To apply the factory settings, separate L+ within 5 seconds of teach-in before switching off the supply voltage.
✓ The device is reset to the factory settings. The device automatically switches to normal operation mode.

7.5 IO-Link

Depending on the device type, the device can exchange process data and parameters via IO-Link. To do this, connect the device to a suitable IO-Link master. A sensor-specific device description file (IODD) is required in the IO-Link master.

The IODD and additional information are available at www.sick.com/UM12.

7.6 SOPAS ET

The SOPAS Engineering Tool (SOPAS ET) software is suitable for parameterization as well as for service and diagnostics purposes. SOPAS ET can be used for device types that come with an IO-Link interface.

Requirements

- A computer with the SOPAS ET software installed on it, and a free USB 2.0 compatible port
- SICK SiLink2 Master (available as accessory)
- Connection cable with M12 male and female connectors, 4-pin (available as accessory)



NOTE

The most up-to-date version of the SOPAS ET software can be downloaded from www.sick.com/SOPAS_ET. The respective system requirements for installing SOPAS ET are also specified there.

Establishing a connection

1. Connect the device to the SiLink2 Master via the male connector or an additional connection cable.
 2. Connect the SiLink2 Master to the computer using the supplied USB cable.
 3. Switch on and start the computer.
 4. To ensure an adequate voltage supply to the device, also connect the enclosed wall plug to the SiLink2 Master.
- ✓ The status LEDs light up green after successful initialization. The device is ready for use.



NOTE

To use SOPAS ET with the device, you need a device description file (SDD) for this device. You can install this within SOPAS ET using the device catalog. The device description file can be installed via the SICK web page (Internet connection required). Follow the instructions in SOPAS ET to do so.

Following installation of the device description file, the device can be selected from the device catalog and added to a project.

A connection to the device is established via the communication interface. The connection must be activated for data transmission (**online**).

8 Maintenance

8.1 Maintenance plan

During operation, the device works maintenance-free.

Table 7: Maintenance plan

Maintenance work	Interval	To be carried out by
Check device and connecting cables for damage at regular intervals.	Depends on ambient conditions and climate.	Specialist
Check the screw connections and plug connectors.	Depends on the place of use, ambient conditions or operating requirements. Recommended: At least every 6 months.	Specialist

8.2 Cleaning



NOTICE

Equipment damage due to improper cleaning.

Improper cleaning may result in equipment damage.

- Only use recommended cleaning agents and tools.
 - Never use sharp objects for cleaning.
-
- Carefully clean the adjoining faces with water at regular intervals.

9 Troubleshooting

9.1 Repairs

Repair work on the device may only be performed by qualified and authorized personnel from SICK AG. Interruptions or modifications to the device by the customer will invalidate any warranty claims against SICK AG.

9.2 Returns

- ▶ Only send in devices after consulting with SICK Service.
- ▶ The device must be sent in the original packaging or an equivalent padded packaging.



NOTE

To enable efficient processing and allow us to determine the cause quickly, please include the following when making a return:

- Details of the contact person
 - Description of the application
 - Description of the fault that occurred
-

9.3 Disposal



CAUTION

Risk of injury due to hot device surface.

The surface of the device can become hot during operation.

- Before performing work on the device (e.g. mounting, cleaning, disassembly), switch off the device and allow it to cool down.
 - Ensure good dissipation of excess heat from the device to the surroundings.
-

If a device can no longer be used, dispose of it in an environmentally friendly manner in accordance with the applicable country-specific waste disposal regulations. Do not dispose of the product along with household waste.



NOTICE

Danger to the environment due to improper disposal of the device.

Disposing of devices improperly may cause damage to the environment.

Therefore, observe the following information:

- Always observe the national regulations on environmental protection.
 - Separate the recyclable materials by type and place them in recycling containers.
-

10 Technical data



NOTE

The relevant online data sheet for your product, including technical data, dimensional drawing, and connection diagrams can be downloaded, saved, and printed from the Internet:

- www.sick.com/UM12

Please note: This documentation may contain further technical data.

10.1 Mechanics/Electronics

	Digital output		Digital output with IO-Link		Analog output	
	UM12-117 2211	UM12-119 2211	UM12-117 22B1	UM12-119 22B1	UM12-1172261	UM12-1192261
	UM12-117 2251	UM12-119 2251			UM12-1172271	UM12-1192271
Supply voltage V _S	DC 10 V ... 30 V ¹⁾				Voltage output: DC 15 V ... 30 V ¹⁾ Current output: DC 10 V ... 30 V at R _L ≤ 100 Ω ¹⁾ DC 15 V ... 30 V at R _L > 100 Ω ¹⁾	
Power consumption	≤ 0.75 W ²⁾	≤ 1.05 W ²⁾	≤ 0.75 W ²⁾	≤ 1.05 W ²⁾	≤ 0.9 W ²⁾	≤ 1.2 W ²⁾
Initialization time	< 300 ms					
Design	Cylindrical					
Housing material	Metal (nickel plated brass, PBT) Ultrasonic converter: Polyurethane foam, epoxy resin with glass content					
Threaded size	M12 x 1					
Connection type	Male connector, M12, 4-pin					
Display	2 x LED					
Weight	15 g					
Sending axis	Straight					
Dimensions (W x H x D)	12 mm x 12 mm x 55.1 mm				12 mm x 12 mm x 60.1 mm	
Enclosure rating	IP65 / IP67 (EN 60529)					
Protection class	III					
Maximum tightening torque for fixing nuts	1 Nm					

1) Limit values, reverse-polarity protected Operation in short-circuit protected network: max. 8 A, class 2.

2) Without load.

10.2 Performance

	Digital output		Digital output with IO-Link		Analog output	
	UM12-117 2211	UM12-119 2211	UM12-117 22B1	UM12-119 22B1	UM12-1172261	UM12-1192261
	UM12-117 2251	UM12-119 2251			UM12-1172271	UM12-1192271
Operating range	20 mm ... 150 mm	40 mm ... 240 mm	20 mm ... 150 mm	40 mm ... 240 mm	20 mm ... 150 mm	40 mm ... 240 mm

	Digital output		Digital output with IO-Link		Analog output	
	UM12-1172211	UM12-1192211	UM12-11722B1	UM12-11922B1	UM12-1172261	UM12-1192261
	UM12-1172251	UM12-1192251			UM12-1172271	UM12-1192271
Limiting range	250 mm	350 mm	250 mm	350 mm	250 mm	350 mm
Measuring object	Natural objects					
Resolution	≥ 0.069 mm					
Repeatability	± 0.15% ¹⁾					
Accuracy	± 1% ²⁾					
Temperature compensation	✓					
Response time	24 ms	30 ms	24 ms	30 ms	24 ms ³⁾	30 ms ³⁾
Switching frequency	30 Hz	25 Hz	30 Hz	25 Hz	-	-
Output time	8 ms	10 ms	8 ms	10 ms	8 ms	10 ms
Ultrasonic frequency (typical)	380 kHz	500 kHz	380 kHz	500 kHz	380 kHz	500 kHz
Additional function	Selectable operating modes: distance to object (DtO), switching window, object between sensor and background (ObSB); teachable digital output; invertible digital output; reset to factory settings ⁴⁾					

1) Relative to the current measured value, minimum value ≥ resolution.

2) Relative to the current measured value.

3) Subsequent smoothing of the analog output may increase the response time by up to 200% in some applications.

4) Functions may vary depending on the sensor variant.

10.3 Interfaces

Device with digital output

	Digital output		Digital output with IO-Link	
	UM12-1172211	UM12-1192211	UM12-11722B1	UM12-11922B1
	UM12-1172251	UM12-1192251		
IO-Link	-		✓, IO-Link V1.1 Function: Process data, configuration, diagnostics, data storage	
digital output	Quantity: 1 Type: PNP ¹⁾ or NPN ²⁾ Maximum output current I_A : ≤ 200 mA		Quantity: 1 Type: Push-pull: PNP/NPN ³⁾ Maximum output current I_A : ≤ 100 mA	
Hysteresis	2 mm	3 mm	2 mm	3 mm

1) PNP: HIGH = $U_V - (< 2 \text{ V})$ / LOW = 0 V.

2) NPN: HIGH ≤ 2 V / LOW = U_V .

3) Push-pull: PNP/NPN: HIGH = $U_V - (< 3 \text{ V})$ / LOW = < 3 V.

Device with analog output

	Analog output
	UM12-1172261, UM12-1172271
Analog output	4 mA ... 20 mA: $R_L \leq 500 \Omega$ ¹⁾ 0 V ... 10 V: $R_L \geq 100 \text{ k}\Omega$
Resolution	12 bit

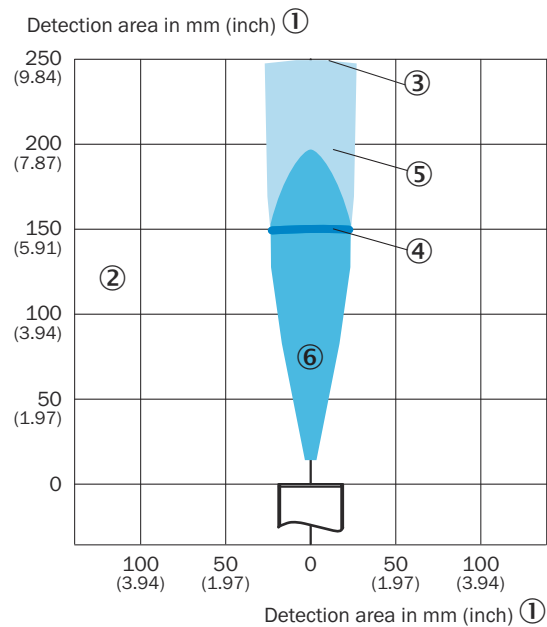
1) At 4 mA ... 20 mA and $U_V \leq 20 \text{ V}$ max. load ≤ 100 Ω .

10.4 Ambient data

Ambient operating temperature	-25 °C ... +70 °C
Storage temperature	-40 °C ... +85 °C

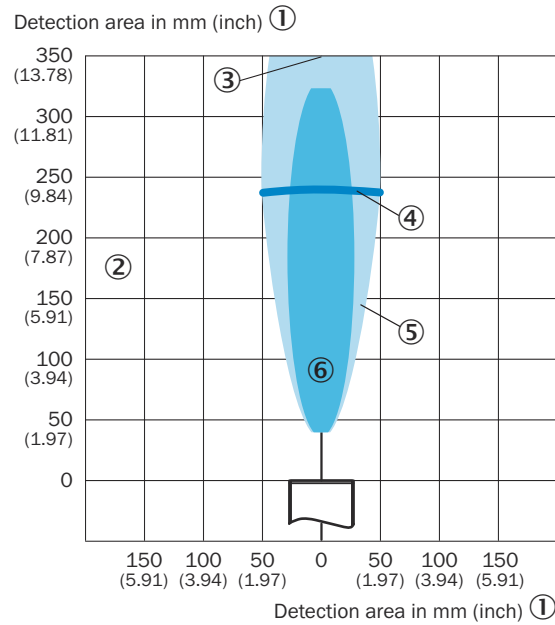
10.5 Detection ranges

UM12-117x



- ① Detection range in mm (inch)
- ② Detection range dependent on reflection properties, size, and alignment of the object
- ③ Limiting range
- ④ Operating range
- ⑤ Example object: aligned plate 500 mm x 500 mm
- ⑥ Example object: Cylindrical bar with diameter of 10 mm

UM12-119x



- ① Detection range in mm (inch)
- ② Detection range dependent on reflection properties, size, and alignment of the object
- ③ Limiting range
- ④ Operating range
- ⑤ Example object: aligned plate 500 mm x 500 mm
- ⑥ Example object: Cylindrical bar with diameter of 10 mm

11 Accessories



NOTE

Accessories and, if applicable, mounting information can be found online at:

- www.sick.com/UM12
-

12 Annex

12.1 Declarations of conformity and certificates

The declarations of conformity and certificates can be downloaded from the Internet at:

- www.sick.com/UM12

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